# $q$-KP hierarchy, bispectrality and Calogero-Moser systems 

Plamen Iliev ${ }^{1}$<br>Department of Mathematics, Université Catholique de Louvain, 1348 Louvain-la-Neuve, Belgium

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#### Abstract

We show that there is a one-to-one correspondence between the $q$-tau functions of a $q$-deformation of the KP hierarchy and the planes in Sato Grassmannian Gr. Using this correspondence, we define a subspace $G r_{q}^{\text {ad }}$ of $G r$, which is a $q$-deformation of Wilson's adelic Grassmannian $G r^{\text {ad }}$. From each plane $W \in G r_{q}^{\text {ad }}$ we construct a bispectral commutative algebra $\mathcal{A}_{W}^{q}$ of $q$-difference operators, which extends to the case $q \neq 1$ all rank one solutions to the bispectral problem. The common eigenfunction $\Psi(x, z)$ for the operators from $\mathcal{A}_{W}^{q}$ is a $q$-wave (Baker-Akhiezer) function for a rational (in $x$ ) solution to the $q$-KP hierarchy. The poles of these solutions are governed by a certain $q$-deformation of the Calogero-Moser hierarchy. © 2000 Elsevier Science B.V. All rights reserved.


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## 1. Introduction

In [16], Frenkel proposed a $q$-deformation of the $N$ th KdV hierarchy which is Hamiltonian with respect to the quantum Poisson algebra $\mathcal{W}_{q}\left(\mathfrak{s l}_{N}\right)$ defined in [17]. A similar deformation of the KP hierarchy was obtained by Khesin et al. [30], who considered a certain $q$-deformation of the Lie algebra of pseudo-differential operators on the circle, see also [35].

In [24], a slightly different deformation of the KP hierarchy was proposed. It was shown that by making an appropriate shift in the arguments of the classical Schur polynomials, one obtains rational solutions of the deformed hierarchy. This result was extended in [1,25],

[^0]where it was proved that the same shift in any classical tau function leads to a solution of the deformed hierarchy.

In the present paper we complete the study of the $q$-tau functions, by showing in Theorem 2.1 that the shift mentioned above characterizes the $q$-tau functions in the ring of formal power series. Thus, we establish, in fact, a one-to-one correspondence between the $q$-tau functions and the planes in Sato Grassmannian.

As a first application of this result we construct a $q$-deformation of Wilson's adelic Grassmannian $G r_{q}^{\text {ad }}$, which parametrizes rank one commutative bispectral algebras of $q$-difference operators. A $q$-difference operator $L\left(x, D_{q, x}\right)$ is called bispectral if it has a family of eigenfunctions $\Psi(x, z)$ that is also a family of eigenfunctions of some $q$-difference operator $B\left(z, D_{q, z}\right)$ in the spectral parameter $z$, i.e.

$$
\begin{align*}
& L\left(x, D_{q, x}\right) \Psi(x, z)=f(z) \Psi(x, z)  \tag{1.1}\\
& B\left(z, D_{q, z}\right) \Psi(x, z)=\theta(x) \Psi(x, z) \tag{1.2}
\end{align*}
$$

Here $D_{q, x}$ denotes the usual $q$-derivative operator acting on functions of $x$

$$
D_{q, x} f(x)=\frac{f(q x)-f(x)}{(q-1) x}
$$

In the limit $q \rightarrow 1, L$ and $B$ become ordinary differential operators. In this context the problem was posed and completely solved for $L$ of order 2 , in the pioneering work of Duistermaat and Grünbaum [15]. It turns out that this problem is intimately related with several actively developing areas of mathematics: integrable systems [15,41,42] and their master symmetries [44], the representation theory of Virasoro and $W_{1+\infty}$ algebras [8], Huygens principle [9], to mention only a few.

Our construction of $G r_{q}^{\text {ad }}$ is inspired by Wilson's approach [41] to the bispectral problem. In view of the works of Burchnall and Chaundy [11-13] and Krichever [31], one may consider any operator $L\left(x, \partial_{x}\right)$ as an element of a maximal commutative algebra $\mathcal{A}$ of differential operators. An important invariant of such an algebra is its rank, i.e., the greatest common divisor of the orders of the operators in the algebra. In [41] Wilson found a beautiful characterization of all rank one solutions to the bispectral problem. He proved that a maximal rank one commutative algebra $\mathcal{A}$ of ordinary differential operators is bispectral if and only if the curve $\operatorname{Spec} \mathcal{A}$ is rational and unicursal (i.e. all singularities are cusps). The bispectrality is a consequence of an extra symmetry in $G r^{\text {ad }}$ called the bispectral involution. Roughly, this is the map which exchanges the role of the arguments in the Baker-Akhiezer function. In the framework of Sato Grassmannian, the rank one bispectral algebras are parametrized by an adelic Grassmannian $G r^{\text {ad }}$, whose points correspond to solutions of the KP hierarchy, arising from unicursal rational curves by Krichever's construction. These solutions are nothing but the rational solutions of the KP hierarchy [32,40,42].

In the last few years, the original results of Duistermaat-Grünbaum and Wilson have been extended in several directions. Bakalov et al. [7] and Kasman and Rothstein [28] constructed bispectral algebras of ordinary differential operators of any rank (see also [6] for an abstract version of the bispectral problem and further examples). In a different vein, Grünbaum and

Haine $[18,19,21]$ started a study of a discrete version of the original problem, by replacing $L$ by a doubly infinite tridiagonal matrix. If one imposes special boundary conditions on the joint eigenfunctions, this problem contains the classical problem of classifying orthogonal polynomials which are eigenfunctions of a differential operator, and leads to extensions of the Askey-Wilson polynomials when $B$ is a $q$-difference operator [4,10,20,22]. For a comprehensive review of the 'difference, differential ( $q$-difference)' bispectral problem we refer the reader to the recent survey paper [23].

The ' $q$-difference, $q$-difference' version of the bispectral problem, that we study in this paper, can be looked up as a natural connection between the different bispectral situations. Indeed, any ' $q$-difference' operator $L\left(x, D_{q, x}\right)$ can be considered as a difference operator if we pose $x=q^{n}$, with $n \in \mathbb{Z}$ and becomes a differential operator in the limit $q \rightarrow 1$ (if it exists). At present, it seems to offer the simplest instance among the various discrete versions of the bispectral problem, which can be solved for arbitrary order operators (at least in rank one). The $q$-deformed Grassmannian $G r_{q}^{\text {ad }}$, that we construct, is still contained in the sub-Grassmannian $G r^{\text {rat }}$ which parametrizes the solutions of the KP hierarchy arising from rational algebraic curves. The intersection $G r_{q}^{\text {ad }} \cap G r^{\text {ad }}$ coincides with the sub-Grassmannian $G r_{0}$ whose tau functions are polynomials in only finitely many time variables $t_{1}, t_{2}, \ldots$ As a consequence, the rational curves corresponding to planes $W \in G r_{q}^{\text {ad }} \backslash G r_{0}$ must have at least one node as a singular point.

Using the correspondence between the $q$-tau functions and the planes in Sato Grassmannian, we construct a commutative algebra $\mathcal{A}_{W}^{q}$ of $q$-difference operators from any plane $W \in G r$. For $W \in G r_{q}^{\text {ad }}$, the corresponding $q$-tau function $\tau_{W}^{q}(x, t)$ is a polynomial in $x$, which allows us to show in Section 3 the existence of a bispectral operator $B\left(z, D_{q, z}\right)$ for any polynomial $\theta(x)$, such that $D_{q, x} \theta(x)$ is divisible by $\tau_{W}^{q}(x q)$. However, in contrast to the $q=1$ case, for a generic plane $W \in G r_{q}^{\text {ad }}$, the tau function $\tau_{W}^{q}(x, t)$ is no longer polynomial in the time variables $t_{1}, t_{2}, \ldots$ In Section 5 we consider such a situation, which corresponds to a specific $N$-soliton solution. Formula (5.11) represents an extension of Shiota-Wilson formula for the rational KP solutions [40,42]. As an immediate consequence, we show that in this case the symmetry $\beta$ in $G r^{\text {ad }}$ can be extended to $G r_{q}^{\text {ad }}$. Moreover, as in the $q=1$ case [42], $\beta$ corresponds to a very simple involution at the level of Calogero-Moser pairs of matrices, see Theorem 5.3.

Finally, in Section 6, we examine the dynamics of the poles of the rational solutions (in $x$ ) to the $q-\mathrm{KP}$ hierarchy and show that the motion is governed by a hierarchy of Hamiltonian systems. The $n$th Hamiltonian, corresponding to the $n$th KP flow, is of the form

$$
H_{n}=(-1)^{n} \frac{[n]_{q}}{n} \operatorname{Tr}\left(Y^{n}\right),
$$

where $Y$ is a deformation of the Calogero-Moser matrix, see Theorem 6.1. This result can be looked up as a $q$-analogue of the mysterious connection between the KP hierarchy and the Calogero-Moser hierarchy $[3,32,40]$. The derivation of the system (6.6) is obtained by a suitable adaptation of the approach of Shiota [40] for the classical case, within the context of the $q$-KP hierarchy. The main difficulty here, compared to the $q=1$ case, comes from the non-triviality of the first $q$-KP flow. The key new ingredient is that $\partial / \partial t_{1}$ can be rewritten
in a Lax form (see Lemma 6.2), which allows us to write the system in the Hamiltonian form above.

Some of the results in the present paper were announced in a brief note [26].

## 2. The $q$-KP hierarchy and algebras of $q$-difference operators

In this section we review briefly a $q$-analogue of the KP hierarchy, introduced in [24]. The exposition is based on a $q$-deformation of Sato theory [14,37] and follows closely [25]. For an alternative approach, using a correspondence with the Toda lattice hierarchy, we refer the reader to [1].

The $q$-derivative $D_{q, x} f$ of a function $f(x)$ is given by

$$
\left(D_{q, x} f\right)(x)=\frac{f(x q)-f(x)}{x(q-1)}, \quad x \neq 0,
$$

and $\left(D_{q, x} f\right)(0)=f^{\prime}(0)$, by continuity, provided $f^{\prime}(0)$ exists. We define $D_{q, x}^{n} \cdot f(x)$ for any $n \in \mathbb{Z}$, as the formal $q$-pseudo-difference operator

$$
D_{q, x}^{n} \cdot f=\sum_{k=0}^{\infty}\binom{n}{k}_{q}\left(D_{q, x}^{k} f\right)\left(x q^{n-k}\right) D_{q, x}^{n-k},
$$

where

$$
\binom{n}{0}_{q}=1, \quad\binom{n}{k}_{q}=\frac{\left(1-q^{n}\right)\left(1-q^{n-1}\right) \cdots\left(1-q^{n-k+1}\right)}{(1-q)\left(1-q^{2}\right) \cdots\left(1-q^{k}\right)}
$$

Consider the formal $q$-pseudo-difference operator

$$
L=D_{q, x}+a_{0}+\sum_{i=1}^{\infty} a_{i} D_{q, x}^{-i} .
$$

The $q$-deformed Kadomtsev-Petviashvili (in short $q$-KP) hierarchy is defined by the Lax equations

$$
\begin{equation*}
\frac{\partial L}{\partial t_{j}}=\left[\left(L^{j}\right)_{+}, L\right], \tag{2.1}
\end{equation*}
$$

where $\left(L^{j}\right)_{+}$denotes the positive part of the pseudo-difference operator $L^{j}$. One can define analogues of the wave function $\Psi^{q}\left(x, t_{1}, t_{2}, \ldots, z\right)$ and the tau function $\tau^{q}\left(x, t_{1}, t_{2}, \ldots\right),{ }^{2}$ which are connected by Sato formula

$$
\begin{align*}
\Psi^{q}\left(x, t_{1}, t_{2}, \ldots, z\right) & =\frac{\tau^{q}\left(x, t_{1}-1 / z, t_{2}-1 / 2 z^{2}, \ldots\right)}{\tau^{q}\left(x, t_{1}, t_{2}, \ldots\right)} e_{q}^{x z} \exp \left(\sum_{i=1}^{\infty} t_{i} z^{i}\right) \\
& =\psi^{q}\left(x, t_{1}, t_{2}, \ldots, z\right) e_{q}^{x z} \exp \left(\sum_{i=1}^{\infty} t_{i} z^{i}\right), \tag{2.2}
\end{align*}
$$

[^1]where
$$
e_{q}^{x}=\sum_{k=0}^{\infty} \frac{(1-q)^{k}}{(1-q)\left(1-q^{2}\right) \cdots\left(1-q^{k}\right)} x^{k}
$$
denotes the $q$-exponential. The operator $L$ is conjugated to $D_{q, x}$ by the wave operator $S=: \psi^{q}\left(x, t_{1}, t_{2}, \ldots, D_{q, x}\right):^{3}$
$$
L=S D_{q, x} S^{-1}
$$

This formula allows us to express all functions $\left\{a_{i}(x, t)\right\}$ in terms of the tau function $\tau^{q}(x, t)$, where we have put $t=\left(t_{1}, t_{2}, \ldots\right)$. In particular, we have

$$
\begin{equation*}
a_{0}(x, t)=\frac{\partial}{\partial t_{1}} \log \frac{\tau^{q}(x q, t)}{\tau^{q}(x, t)} \tag{2.3}
\end{equation*}
$$

The KP flows are represented on the wave function by the formulae

$$
\begin{equation*}
\frac{\partial \Psi^{q}}{\partial t_{k}}=\left(L^{k}\right)_{+} \Psi^{q} \tag{2.4}
\end{equation*}
$$

for $k=1,2, \ldots$ and the operator $L$ acts as a multiplication by $z$

$$
\begin{equation*}
L \Psi^{q}=z \Psi^{q} \tag{2.5}
\end{equation*}
$$

From (2.3) and (2.4) for $k=1$ we get

$$
\begin{equation*}
\frac{\partial \Psi^{q}}{\partial t_{1}}(x, t, z)=\left(D_{q, x}+\frac{\partial}{\partial t_{1}} \log \frac{\tau^{q}(x q, t)}{\tau^{q}(x, t)}\right) \Psi^{q}(x, t, z) \tag{2.6}
\end{equation*}
$$

The last equality, combined with the fact that $\tau^{q}(x, t)$ is a tau function in the sense of Kyoto school for any $x$ fixed, characterizes completely the $q$-tau functions. The next theorem gives a simple explicit description of the $q$-tau functions in terms of the classical tau functions.

Theorem 2.1. A formal power series $\tau^{q}(x, t) \in \mathbb{C}\left[\left[x, t_{1}, t_{2}, \ldots\right]\right]$ is a tau function for the $q-K P$ hierarchy if and only if, up to an unessential factor depending only on $x$, we have

$$
\begin{equation*}
\tau^{q}(x, t)=\tilde{\tau}\left(t+[x]_{q}\right) \tag{2.7}
\end{equation*}
$$

where $\tilde{\tau}(t) \in \mathbb{C}\left[\left[t_{1}, t_{2}, \ldots\right]\right]$ is a tau function for the classical KP hierarchy, and

$$
[x]_{q}=\left(x, \frac{(1-q)^{2}}{2\left(1-q^{2}\right)} x^{2}, \frac{(1-q)^{3}}{3\left(1-q^{3}\right)} x^{3}, \ldots\right)
$$

Proof. The 'if' part was proved in [1,25]. Below we prove the 'only if' part of the theorem. From (2.2) it is clear that if we multiply $\tau^{q}$ by a function which depends only on $x$, we get another tau function for the same solution. Thus, without any restriction, we may

[^2]suppose that $\tau^{q}(0, t) \not \equiv 0$. Plugging (2.2) in (2.6) and cancelling the exponential part we get
\[

$$
\begin{align*}
& \left(z+\frac{1}{x(q-1)}\right)\left(\frac{\tau^{q}\left(x q, t-\left[z^{-1}\right]\right)}{\tau^{q}(x q, t)}-\frac{\tau^{q}\left(x, t-\left[z^{-1}\right]\right)}{\tau^{q}(x, t)}\right) \\
& \quad=\frac{\tau^{q}\left(x, t-\left[z^{-1}\right]\right)}{\tau^{q}(x, t)}\left(\frac{\partial}{\partial t_{1}} \log \tau^{q}\left(x, t-\left[z^{-1}\right]\right)-\frac{\partial}{\partial t_{1}} \log \tau^{q}(x q, t)\right), \tag{2.8}
\end{align*}
$$
\]

where

$$
[z]=[z]_{0}=\left(z, \frac{z^{2}}{2}, \frac{z^{3}}{3}, \ldots\right)
$$

If we put $z=-1 / x(q-1)$ in the above identity we obtain

$$
\frac{\partial}{\partial t_{1}} \log \tau^{q}(x, t-[x(1-q)])=\frac{\partial}{\partial t_{1}} \log \tau^{q}(x q, t)
$$

and we can rewrite (2.8) as

$$
\begin{align*}
& \frac{\tau^{q}\left(x q, t-\left[z^{-1}\right]\right)}{\tau^{q}(x q, t)}-\frac{\tau^{q}\left(x, t-\left[z^{-1}\right]\right)}{\tau^{q}(x, t)} \\
& =\left(z+\frac{1}{x(q-1)}\right)^{-1} \frac{\left\{\tau^{q}\left(x, t-\left[z^{-1}\right]\right), \tau^{q}(x, t-[x(1-q)])\right\}}{\tau^{q}(x, t) \tau^{q}(x, t-[x(1-q)])} \tag{2.9}
\end{align*}
$$

with

$$
\{f, g\}:=\frac{\partial f}{\partial t_{1}} g-f \frac{\partial g}{\partial t_{1}} .
$$

Since $\tau^{q}(x, t)$ is a classical tau function in $t_{1}, t_{2}, \ldots$, it satisfies the differential Fay identity due to Adler and van Moerbeke [2]

$$
\begin{align*}
& \frac{\left\{\tau^{q}\left(x, t-\left[z^{-1}\right]\right), \tau^{q}\left(x, t-\left[y^{-1}\right]\right)\right\}}{z-y} \\
& \quad=-\tau^{q}\left(x, t-\left[z^{-1}\right]\right) \tau^{q}\left(x, t-\left[y^{-1}\right]\right)+\tau^{q}(x, t) \tau^{q}\left(x, t-\left[z^{-1}\right]-\left[y^{-1}\right]\right) . \tag{2.10}
\end{align*}
$$

For $y^{-1}=x(1-q)$ from (2.9) and (2.10) we get

$$
\begin{equation*}
\frac{\tau^{q}\left(x q, t-\left[z^{-1}\right]\right)}{\tau^{q}(x q, t)}=\frac{\tau^{q}\left(x, t-\left[z^{-1}\right]-[x(1-q)]\right)}{\tau^{q}(x, t-[x(1-q)])} \tag{2.11}
\end{equation*}
$$

Let us consider a new tau function $\tilde{\tau}(x, t):=\tau^{q}\left(x, t-[x]_{q}\right)$. Replacing $t$ by $t-[x q]_{q}$ in (2.11) and using that $[x q]_{q}+[x(1-q)]=[x]_{q}$ we obtain

$$
\frac{\tilde{\tau}\left(x q, t-\left[z^{-1}\right]\right)}{\tilde{\tau}(x q, t)}=\frac{\tilde{\tau}\left(x, t-\left[z^{-1}\right]\right)}{\tilde{\tau}(x, t)} .
$$

The last equality simply means that the ratio $\tilde{\tau}\left(x, t-\left[z^{-1}\right]\right) / \tilde{\tau}(x, t)$ does not depend on $x$, and so we have

$$
\frac{\tilde{\tau}\left(x, t-\left[z^{-1}\right]\right)}{\tilde{\tau}\left(0, t-\left[z^{-1}\right]\right)}=\frac{\tilde{\tau}(x, t)}{\tilde{\tau}(0, t)} .
$$

From this equation it follows that $\tilde{\tau}(x, t) / \tilde{\tau}(0, t)=f(x)$ does not depend on $t_{1}, t_{2}, \ldots$ Thus, we finally obtain

$$
\tau^{q}(x, t)=f(x) \tilde{\tau}\left(0, t+[x]_{q}\right)
$$

which finishes the proof of the theorem.
Using this simple correspondence between the $q$-tau functions and the classical tau functions we can construct commutative algebras $\mathcal{A}_{W}^{q}$ of $q$-difference operators from any plane $W$ from Sato Grassmannian. The $q$-wave function $\Psi_{W}^{q}(x, t, z)=\Psi_{W}\left(t+[x]_{q}, z\right)$ constructed in Theorem 2.1 can be characterized as the unique function $\Psi_{W}^{q}(x, t, z) \in W$ of the form

$$
\Psi_{W}^{q}(x, t, z)=\left(1+\sum_{i=1}^{\infty} \alpha_{i}(x, t) z^{-i}\right) e_{q}^{x z} \exp \left(\sum_{i=1}^{\infty} t_{i} z^{i}\right)
$$

Consider the algebra $A_{W}$ of meromorphic functions $f(z)$ with poles only at $z=\infty$ that leave $W$ invariant:

$$
A_{W}=\{f(z): f(z) W \subset W\}
$$

From the above characterization of the $q$-wave function $\Psi^{q}(x, t, z)$ and the definition of $A_{W}$, one can easily show that for any $f(z) \in A_{W}$, there exists a $q$-difference operator $L_{f}\left(x, t, D_{q, x}\right)$ such that

$$
\begin{equation*}
L_{f}\left(x, t, D_{q, x}\right) \Psi_{W}^{q}(x, t, z)=f(z) \Psi_{W}^{q}(x, t, z) \tag{2.12}
\end{equation*}
$$

If $L_{W}$ denotes the solution of the $q$-KP hierarchy, corresponding to the plane $W$, from (2.5) we can write the following 'explicit' formula for $L_{f}\left(x, t, D_{q, x}\right)$ :

$$
\begin{equation*}
L_{f}\left(x, t, D_{q, x}\right)=f\left(L_{W}\right) \tag{2.13}
\end{equation*}
$$

Now, if we define

$$
\mathcal{A}_{W}^{q}=\left\{L_{f}\left(x, 0, D_{q, x}\right): f(z) \in A_{W}\right\}
$$

we obtain a commutative algebra of $q$-difference operators isomorphic to $A_{W}$ with common eigenfunction $\bar{\Psi}_{W}^{q}(x, z)=\Psi_{W}^{q}(x, 0, z)$. This algebra is non-trivial if $W$ corresponds to an algebro-geometric solution of the KP hierarchy, see [31,34,38]. The spaces $W$ arising from algebro-geometric data are precisely those such that $A_{W}$ contains an element of any sufficiently large order. In the next section we shall use the above construction for the sub-Grassmannian $G r^{\text {rat }}$, consisting of planes $W \in G r$, corresponding to rational algebraic curves. ${ }^{4}$ In this case $A_{W} \subset \mathbb{C}[z]$.

[^3]
## 3. The $q$-adelic Grassmannian $G r_{q}^{\text {ad }}$ and the bispectral problem

In this section we define $G r_{q}^{\text {ad }}$ and show the bispectrality of the corresponding algebras of $q$-difference operators. The proof is based on a $q$-version of the lemma due to Reach [36], which was used in [24] to prove the bispectral property of the $q$-deformed Schur polynomials. In the $q=1$ case, this lemma was first explored by Zubelli [43], who showed the bispectral property of the classical Schur polynomials, and later by Liberati [33] who extended the construction to the adelic Grassmannian.

Inspired by Wilson [41], we consider the linear functionals (q-conditions) $e_{q}(m, \lambda)$ on $\mathbb{C}[z]$, defined by

$$
\left\langle e_{q}(m, \lambda), g\right\rangle=\left(D_{q, z}^{m} g\right)(\lambda),
$$

for $m \geq 0$ and $\lambda \in \mathbb{C}$. We denote by $\mathcal{C}_{\lambda}^{q}$ the infinite dimensional space over $\mathbb{C}$, generated by $e_{q}(m, \lambda)$ for $m \geq 0$, and by $\mathcal{C}^{q}$ the infinite dimensional space over $\mathbb{C}$, generated by all $q$-conditions. In contrast to the classical case, $e_{q}(m, \lambda)$ are no longer linearly independent. It is obvious from the definition that, for $\lambda \neq 0$,

$$
\cdots \subset \mathcal{C}_{\lambda q^{2}}^{q} \subset \mathcal{C}_{\lambda q}^{q} \subset \mathcal{C}_{\lambda}^{q} \subset \mathcal{C}_{\lambda q^{-1}}^{q} \subset \mathcal{C}_{\lambda q^{-2}}^{q} \subset \cdots .
$$

A functional $c$ is called a one point $q$-condition if it is a finite linear combination of $q$-conditions supported at single point $\lambda$, i.e. $c \in \mathcal{C}_{\lambda}^{q}$. For each finite dimensional subspace $C \subset \mathcal{C}^{q}$, we set

$$
V_{C}=\{g(z) \in \mathbb{C}[z]:\langle c, g\rangle=0 \quad \text { for } c \in C\} .
$$

Now we are ready to give the definition of the $q$-deformed adelic Grassmannian $G r_{q}^{\text {ad }}$.
Definition 3.1. A plane $W \in G r$ belongs to $G r_{q}^{\text {ad }}$ if $W$ has the form $W=r^{-1}(z) V_{C}$, for some finite dimensional subspace $C \subset \mathcal{C}^{q}$, which possesses a basis of one-point $q$-conditions, and $r(z)$ is the unique polynomial in $z$ of degree $\operatorname{deg} r(z)=\operatorname{dim} C$, such that

$$
\left.\lim _{x \rightarrow \infty} \psi_{W}^{q}\right|_{t=0}=1
$$

Remark 3.2. From the definition it follows directly that $G r_{q}^{\text {ad }}$ is contained in the Grassmannian $G r^{\text {rat }}$, which corresponds to the algebro-geometric solutions of the KP hierarchy, arising from rational algebraic curves, see [41]. In particular, for any $W \in G r_{q}^{\text {ad }}, S$ Sec $A_{W}$ is a rational curve. The intersection $G r^{\text {ad }} \cap G r_{q}^{\text {ad }}$ is the sub-Grassmannian $G r_{0}$, corresponding to planes $W \in G r$, with a tau function $\tau_{W}(t)$ polynomial in a finite number of the time variables $t_{1}, t_{2}, \ldots$.

Remark 3.3. The group $\Gamma_{-}$of rational functions $\gamma(z)$ with $\gamma(\infty)=1$ acts ${ }^{5}$ on Gr $^{\text {rat }}$ by scalar multiplication and the $q$-wave function of $\gamma(z) W$ is just $\gamma(z) \Psi_{W}^{q}$. Thus, the algebra

[^4]$\mathcal{A}_{W}^{q}$ constructed from $W$ depends only on the $\Gamma_{-}$-orbit in $G r^{\text {rat }}$, which gives us some freedom in choosing $r(z)$. The special choice of $r(z)$ above is made to fix the plane in each orbit of $\Gamma_{-}$, whose tau function is, up to an unessential factor, a polynomial in $x$ with constant leading coefficient (i.e. it can be taken to be a monic polynomial). This normalization is used for the extension of the bispectral involution in Section 5. The explicit formula for $r(z)$ will be computed later (see (3.7)).

Let us fix a plane $W=r^{-1}(z) V_{C} \in G r_{q}^{\text {ad }}$ with $C=\left\{c_{1}, c_{2}, \ldots, c_{N}\right\}$ as in the definition. Since $\left\{c_{i}\right\}$ are one point $q$-conditions we can write

$$
c_{k}=\sum_{i=1}^{s_{k}} \gamma_{k i} e_{q}\left(i, \lambda_{k}\right)
$$

where $s_{k}$ is the order ${ }^{6}$ of the condition $c_{k}$. From the characterization of the $q$-wave function in the previous section and the definition of $W$, one obtains the following explicit formula for $\Psi_{W}^{q}(x, t, z)$ :

$$
\begin{equation*}
\Psi_{W}^{q}(x, t, z)=\frac{1}{r(z)} \frac{\operatorname{Wr}_{q}\left(f_{1}, f_{2}, \ldots, f_{N}, e_{q}^{x z}\right)}{\operatorname{Wr}_{q}\left(f_{1}, f_{2}, \ldots, f_{N}\right)} \exp \left(\sum_{k=1}^{\infty} t_{k} z^{k}\right) \tag{3.1}
\end{equation*}
$$

where $f_{k}(x, t)=\left\langle c_{k}, e_{q}^{x z} \exp \left(\sum t_{i} z^{i}\right)\right\rangle$, and $\operatorname{Wr}_{q}\left(f_{1}, \ldots, f_{N}\right)$ denotes the $q$-Wronskian determinant $\operatorname{det}\left(D_{q, x}^{i-1} f_{j}\right)$. From the defining relation of $\left\{f_{k}\right\}$, it is not difficult to check that they satisfy

$$
\begin{equation*}
f_{k}\left(x, t-\left[z^{-1}\right]\right)=f_{k}(x, t)-\frac{1}{z} D_{q, x} f_{k}(x, t) \tag{3.2}
\end{equation*}
$$

Using (3.1) and (3.2) and the elementary properties of determinants we can rewrite $\Psi_{W}^{q}$ $(x, t, z)$ in the form

$$
\begin{align*}
& \Psi_{W}^{q}(x, t, z) \\
& =\frac{z^{N}}{r(z)} \frac{\operatorname{Wr}_{q}\left(f_{1}\left(x, t-\left[z^{-1}\right]\right), \ldots, f_{N}\left(x, t-\left[z^{-1}\right]\right)\right)}{\operatorname{Wr}_{q}\left(f_{1}(x, t), \ldots, f_{N}(x, t)\right)} e_{q}^{x z} \exp \left(\sum_{k=1}^{\infty} t_{k} z^{k}\right) \tag{3.3}
\end{align*}
$$

From the last equality, it follows that $\tau_{W}^{q}(x, t)$ is a polynomial in $x$ given by

$$
\begin{equation*}
\tau_{W}^{q}(x, t)=\mathrm{Wr}_{q}\left(f_{1}, f_{2}, \ldots, f_{N}\right)\left(e_{q}^{\lambda_{1} x} \cdots e_{q}^{\lambda_{N} x}\right)^{-1} \exp \left(\sum_{i=1}^{\infty} \beta_{i} t_{i}\right) \tag{3.4}
\end{equation*}
$$

where $\left\{\beta_{i}\right\}$ are constants determined by the equality

$$
\frac{r(z)}{z^{N}}=\exp \left(\sum_{i=1}^{\infty} \frac{\beta_{i}}{i z^{i}}\right)
$$

[^5]Substituting $t_{1}=t_{2}=\cdots=0$ in (3.1) and (3.4) we obtain

$$
\begin{align*}
& \bar{\tau}_{W}^{q}(x):=\tau_{W}^{q}(x, 0)=\mathrm{Wr}_{q}\left(p_{1}(x) e_{q}^{\lambda_{1} x}, \ldots, p_{N}(x) e_{q}^{\lambda_{N} x}\right)\left(e_{q}^{\lambda_{1} x} \cdots e_{q}^{\lambda_{N} x}\right)^{-1}  \tag{3.5}\\
& \bar{\Psi}_{W}^{q}(x, z)=\Psi_{W}^{q}(x, 0, z)=\frac{\mathrm{Wr}_{q}\left(p_{1}(x) e_{q}^{\lambda_{1} x}, \ldots, p_{N}(x) e_{q}^{\lambda_{N} x}, e_{q}^{x z}\right)}{r(z) \tau_{W}^{q}(x, 0) e_{q}^{\lambda_{1} x} \cdots e_{q}^{\lambda_{N} x}} \tag{3.6}
\end{align*}
$$

where $p_{k}(x)=f_{k}(x, 0)\left(e_{q}^{\lambda_{k} x}\right)^{-1}=\sum_{i=1}^{s_{k}} \gamma_{k i} x^{i}$ for $k=1,2, \ldots, N$ and $\bar{\tau}_{W}^{q}(x)$ are polynomials in $x$.

To write an explicit formula for $r(z)$ we shall suppose that $\lambda_{i} q^{s_{i}} \neq \lambda_{j} q^{s_{j}}$ for $i \neq j$. This inequality can always be achieved by picking an appropriate basis of $C$. Indeed, $\lambda_{i} q^{s_{i}}=$ $\lambda_{j} q^{s_{j}}$ means that $c_{i}$ and $c_{j}$ can be looked up as conditions of the same order supported at the point $\lambda_{i} q^{-s}$ for some $s$ big enough; taking appropriate linear combinations we may assume that this never happens. Now, in the limit $x \rightarrow \infty$, from (3.5) and (3.6) one can deduce that

$$
\begin{equation*}
r(z)=\prod_{k=1}^{N}\left(z-\lambda_{k} q^{s_{k}}\right) \tag{3.7}
\end{equation*}
$$

Let us now formulate a $q$-analogue of the lemma due to Reach [36].
Lemma 3.4. Let $g_{0}, g_{1}, \ldots, g_{N+1}$ be functions of $x$. Define

$$
\begin{equation*}
G(x)=\sum_{k=1}^{N+1}(-1)^{N+1+k} g_{k}(x) \int g_{0}(x) \mathrm{Wr}_{q}\left(g_{1}, \ldots, \hat{g}_{k}, \ldots, g_{N+1}\right) \mathrm{d}_{q} x \tag{3.8}
\end{equation*}
$$

Then

$$
\begin{equation*}
\mathrm{Wr}_{q}\left(g_{1}, g_{2}, \ldots, g_{N}, G\right)=\theta(x) \mathrm{Wr}_{q}\left(g_{1}, g_{2}, \ldots, g_{N+1}\right) \tag{3.9}
\end{equation*}
$$

with

$$
\begin{equation*}
\theta(x)=\left.\left(\int g_{0}(x) \mathrm{Wr}_{q}\left(g_{1}, g_{2}, \ldots, g_{N}\right) \mathrm{d}_{q} x\right)\right|_{x q} \tag{3.10}
\end{equation*}
$$

where $\int \mathrm{d}_{q} x$ denotes the standard $q$-integral.
The proof of this simple but important lemma can be found in [24]. We can now state the main result of this section.

Theorem 3.5. For each plane $W \in G r_{q}^{\text {ad }}$ the commutative algebra of $q$-difference operators $\mathcal{A}_{W}^{q}$ is bispectral. Precisely, the function $\bar{\Psi}_{W}^{q}(x, z)$ satisfies

$$
\begin{equation*}
L_{f}\left(x, D_{q, x}\right) \bar{\Psi}_{W}^{q}(x, z)=f(z) \bar{\Psi}_{W}^{q}(x, z) \tag{3.11}
\end{equation*}
$$

for $f(z) \in A_{W}$, and if $\theta(x)$ is a polynomial in $x$ such that $D_{q, x} \theta(x)$ is divisible by $\bar{\tau}_{W}^{q}(x q)$, there exists a q-difference operator in $z, B_{\theta}\left(z, D_{q, z}\right)$ independent of $x$ such that

$$
\begin{equation*}
B_{\theta}\left(z, D_{q, z}\right) \bar{\Psi}_{W}^{q}(x, z)=\theta(x) \bar{\Psi}_{W}^{q}(x, z) \tag{3.12}
\end{equation*}
$$

Proof. By $q$-integration by parts, for any polynomial $h(x)$, we have

$$
\begin{align*}
& \int h(x) e_{q}^{x z}\left(e_{q}^{\lambda x}\right)^{-1} \mathrm{~d}_{q} x \\
& =-\sum_{k=0}^{\infty} \frac{(\lambda(q-1) x+q)\left(\lambda(q-1) x+q^{2}\right) \cdots\left(\lambda(q-1) x+q^{k+1}\right)}{q^{k(k+1) / 2}(\lambda-q z)\left(\lambda-q^{2} z\right) \cdots\left(\lambda-q^{k+1} z\right)} \\
& \quad \times\left(D_{q, x}^{k} h\right)\left(\frac{x}{q^{k+1}}\right) e_{q}^{x z}\left(e_{q}^{\lambda x}\right)^{-1} . \tag{3.13}
\end{align*}
$$

Now we apply Lemma 3.4 with $g_{0}(x)=p(x) \prod_{i=1}^{N}\left(e_{q}^{\lambda_{i} x}\right)^{-1}$, where $p(x)$ is a polynomial in $x, g_{i}(x)=p_{i}(x) e_{q}^{\lambda_{i} x}$ for $i=1,2, \ldots, N$, and $g_{N+1}=e_{q}^{x z} / r(z)$. Using (3.13) we see that $G$ can be written as

$$
G=P(x, z) e_{q}^{x z}
$$

where $P(x, z)$ is a polynomial in $x$ with rational in $z$ coefficients. Thus, replacing $x e_{q}^{x z}$ by $D_{q, z} e_{q}^{x z}$ we get

$$
\begin{equation*}
G=: P\left(D_{q, z}, z\right): e_{q}^{x z}=B\left(z, D_{q, z}\right) \frac{e_{q}^{x z}}{r(z)} \tag{3.14}
\end{equation*}
$$

Putting (3.14) into (3.9) and using (3.5) and (3.6), we obtain

$$
B\left(z, D_{q, z}\right) \bar{\Psi}_{W}^{q}(x, z)=\theta(x) \bar{\Psi}_{W}^{q}(x, z)
$$

with

$$
\theta(x)=\left.\left(\int p(x) \bar{\tau}_{W}^{q}(x) \mathrm{d}_{q} x\right)\right|_{x q}
$$

from which it follows that $\theta(x)$ can be any polynomial in $x$ such that $D_{q, x} \theta(x)$ is divisible by $\bar{\tau}_{W}^{q}(x q)$.

We shall illustrate all steps of the above construction in the next section.

## 4. Some elementary examples

In this section we present a few simple examples of bispectral algebras of $q$-difference operators.

Example 4.1. As a first example let us take $W$ to be the space of $G r_{0}=G r^{\text {ad }} \cap G r_{q}^{\text {ad }}$ determined by the single condition $\langle c, g\rangle=g^{\prime \prime}(0)-\alpha g^{\prime}(0)$, where $\alpha$ is some parameter. This corresponds to a situation slightly more complicated from the one considered in [24] with a tau function which is a finite linear combination of Schur polynomials. The curve Spec $A_{W}$ has just one cusp at the origin. In fact we have $A_{W}=\mathbb{C}\left[z^{3}, z^{4}, z^{5}\right]$, so the singularity at zero is not planar. Since $z^{3} \in A_{W}$, the $q$-pseudo-difference operator $L_{W}$ solves the third

Gelfand-Dickey (or the third KdV) hierarchy, i.e. $\tilde{L}=L_{W}^{3}$ is a $q$-difference operator. From (3.4) the $q$-tau function for the corresponding plane

$$
W=\frac{1}{z}\left\{g(z) \in \mathbb{C}[z]: g^{\prime \prime}(0)-\alpha g^{\prime}(0)=0\right\}
$$

is

$$
\tau_{W}^{q}(x, t)=\frac{2}{1+q} x^{2}+\left(2 t_{1}-\alpha\right) x+t_{1}^{2}-\alpha t_{1}+2 t_{2}
$$

Hence

$$
\bar{\tau}_{W}^{q}(x)=\frac{2}{1+q} x^{2}-\alpha x .
$$

The wave function, computed at $t_{1}=t_{2}=\cdots=0$ is given by formula (3.6)

$$
\bar{\Psi}_{W}^{q}(x, z)=\left(1+\frac{(q+1)(\alpha-2 x)}{z\left(2 x^{2}-\alpha(q+1) x\right)}\right) e_{q}^{x z}
$$

If we take $f(z)=z^{3} \in A_{W}$ one computes that

$$
\begin{aligned}
\tilde{L}=L_{f}= & D_{q, x}^{3}+\frac{\left(1-q^{3}\right)(1+q)\left(4 q^{3} x^{2}-2 \alpha\left(q^{3}+1\right) x+\alpha^{2}(q+1)\right)}{q^{3} x(2 x-\alpha(q+1))\left(2 q^{3} x-\alpha(q+1)\right)} D_{q, x}^{2} \\
& -\frac{(q+1)\left(q^{2}+q+1\right)}{q^{4} x^{2}} \\
& \times \frac{\left(8 q^{6} x^{3}-4 \alpha q^{3}\left(q^{2}+1\right)(q+1) x^{2}+2 \alpha^{2}\left(2 q^{3}+1\right)(q+1) x-\alpha^{3}(q+1)^{2}\right)}{(2 x-\alpha(q+1))\left(2 q^{2} x-\alpha(q+1)\right)\left(2 q^{3} x-\alpha(q+1)\right)} D_{q, x} \\
& +\frac{\alpha^{2}(q+1)^{3}\left(q^{2}+q+1\right)\left(2\left(q^{2}-q+1\right) x-\alpha\right)}{q^{4} x^{3}(2 x-\alpha(q+1))\left(2 q^{2} x-\alpha(q+1)\right)\left(2 q^{3} x-\alpha(q+1)\right)} .
\end{aligned}
$$

We choose

$$
\theta(x)=x^{3}-\frac{\alpha}{2 q}\left(q^{2}+q+1\right) x^{2}
$$

such that

$$
D_{q, x} \theta(x)=\frac{\left(q^{2}+q+1\right)(1+q)}{2 q^{2}} \bar{\tau}_{W}^{q}(x q)
$$

The bispectral operator $B_{\theta}\left(z, D_{q, z}\right)$ is given by the formula

$$
\begin{aligned}
B_{\theta}\left(z, D_{q, z}\right)= & D_{q, z}^{3}-\frac{\left(q^{2}+q+1\right)\left(\alpha q^{2} z+2 q^{2}-2\right)}{2 q^{3} z} D_{q, z}^{2} \\
& +\frac{(q+1)\left(q^{2}+q+1\right)(\alpha(q-1) z-2)}{2 q^{3} z^{2}} D_{q, z} \\
& +\frac{\alpha(q+1)\left(q^{2}+q+1\right)}{2 q^{3} z^{2}} .
\end{aligned}
$$

The next example deals with the simplest possible plane $W$ belonging to $G r_{q}^{\text {ad }}$ but not to $G r^{\text {ad }}$.

Example 4.2. Let $C=\mathbb{C} e_{q}(1,1)$ be the space generated by the single condition $e_{q}(1,1)$ at the point $z=1$. For $q \neq 1$ this is the simplest example of soliton solution of the KP hierarchy, consisting of a solitary wave. We have that $r(z)=z-q$ and the $q$-tau function for the corresponding plane $W=r^{-1} V_{C}$ is given by formula (3.4)

$$
\tau_{W}^{q}(x, t)=x+\frac{\exp \left(\sum_{i=1}^{\infty} t_{i} q^{i}\right)-\exp \left(\sum_{i=1}^{\infty} t_{i}\right)}{q-1}
$$

Thus

$$
\bar{\tau}_{W}^{q}(x)=x
$$

The wave function, computed at $t_{1}=t_{2}=t_{3}=\cdots=0$, is

$$
\bar{\Psi}_{W}^{q}(x, z)=\left(1-\frac{1}{x(z-q)}\right) e_{q}^{x z}
$$

The algebra $A_{W}$ is generated by

$$
f(z)=z^{2}-(q+1) z+q
$$

and

$$
h(z)=z^{3}-\frac{3}{2}(q+1) z^{2}+\frac{1}{2}\left(q^{2}+4 q+1\right) z-\frac{1}{2}\left(q^{2}+q\right)
$$

where

$$
L_{f}=D_{q, x}^{2}-\frac{(q+1)\left(q^{2} x+q-1\right)}{q^{2} x} D_{q, x}+\frac{\left(q^{3} x^{2}-q-1\right)}{q^{2} x^{2}}
$$

If we choose for example $\theta=x^{2}$, the bispectral operator $B_{\theta}\left(z, D_{q, z}\right)$ becomes

$$
B_{\theta}\left(z, D_{q, z}\right)=D_{q, z}^{2}+\frac{\left(1-q^{2}\right) z}{q(z-q)(z q-1)} D_{q, z}-\frac{q+1}{q(z-q)(z q-1)}
$$

Let us take $\xi=f(z)$ and $\eta=h(z)$ as generators of the coordinate ring. The corresponding curve is

$$
\eta^{2}=\xi^{3}+\left(\frac{q-1}{2}\right)^{2} \xi^{2}
$$

The sole singularity is a double point at the origin which becomes a cusp in the limit $q \rightarrow 1$, in agreement with Wilson's result.

Remark 4.3. Using the above examples one can easily understand the picture in general. For a plane from the 'non-deformed' part $G r_{0}=G r^{\text {ad }} \cap G r_{q}^{\text {ad }}$, the tau function is a polynomial in finitely many time variables and we have a rational solution of the $q-K P$ hierarchy (in all variables). In terms of Darboux transformation (see $[5,6,33]$ ) this corresponds to
bispectral operators obtained by factorizing some powers of $D_{q, x}$. In the case of Example 4.1, the operator $\tilde{L}=L_{f}$ is a Darboux transformation from the operator $f\left(D_{q, x}\right)=D_{q, x}^{3}$.

When we have conditions supported 'outside 0', we get soliton-like solutions of the $q$-KP hierarchy, which are rational in $x$, and which are rational in all time-variables in the limit $q \rightarrow 1$. This corresponds to some deformation of the constant coefficient operator from which we do the Darboux transformation. In Example 4.2 the operator $L_{f}$ is a Darboux transformation from the second order q-difference operator

$$
f\left(D_{q, x}\right)=\left(D_{q, x}-1\right)\left(D_{q, x}-q\right)
$$

Note also that the operator $\left(D_{q, x}-1\right)^{2}$ cannot be 'rationally' factorized in a different way. In general, one would easily show that the bispectral operators parametrized by $G r_{q}^{\text {ad }}$ can be described as Darboux transformations from constant coefficient q-difference operators of the form

$$
L=\prod_{i=1}^{N} \prod_{j=1}^{k_{i}}\left(D_{q, x}-\lambda_{i} q^{j-1}\right)
$$

In the next section, we consider the 'generic' case of planes generated by first order conditions at different points and show that in this case the bispectral property is related to a symmetry in $G r_{q}^{\text {ad }}$. In the case $q=1$, this is the clue to the connection with the Calogero-Moser system (see [27,42]).

## 5. q-Calogero-Moser matrix and the bispectral problem

Let us take first order conditions $\left\{c_{1}, \ldots, c_{N}\right\}$, supported at different points $\left\{\lambda_{1}, \ldots, \lambda_{N}\right\}$, which satisfy also ${ }^{7} \lambda_{i} \neq q \lambda_{j}$ for $i \neq j$, i.e. $c_{i}=e_{q}\left(1, \lambda_{i}\right)+\alpha_{i} e_{q}\left(0, \lambda_{i}\right)$ and consider the plane

$$
\begin{equation*}
W=\prod_{j=1}^{N}\left(z-q \lambda_{j}\right)^{-1} V_{C} \tag{5.1}
\end{equation*}
$$

Let us denote by $\Lambda$ and $\alpha$ the diagonal matrices $\Lambda=\operatorname{diag}\left(\lambda_{1}, \lambda_{2}, \ldots, \lambda_{N}\right)$ and $\alpha=$ $\operatorname{diag}\left(\alpha_{1}, \alpha_{2}, \ldots, \alpha_{N}\right)$, and by $\operatorname{Van}(\lambda)=\left(\lambda_{i}^{j-1}\right)_{1 \leq i, j \leq N}-$ the Vandermonde matrix. Now, using (3.4) one can write the tau function in the form

$$
\begin{align*}
& \tau_{W}^{q}(x, t)=\operatorname{det}[x \operatorname{Van}(q \lambda)+V \\
& \left.+\operatorname{Van}(\lambda)\left(\alpha \exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)+\frac{\exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)-E}{1-q} \Lambda^{-1}\right)\right] \tag{5.2}
\end{align*}
$$

[^6]where $\operatorname{Van}(q \lambda)=\operatorname{Van}\left(q \lambda_{1}, q \lambda_{2}, \ldots, q \lambda_{N}\right), E=E_{N}$ is the identity $N \times N$ matrix and
\[

V=\left($$
\begin{array}{cccc}
0 & 0 & \cdots & 0 \\
1 & 1 & \cdots & 1 \\
{[2]_{q} \lambda_{1}} & {[2]_{q} \lambda_{2}} & \cdots & {[2]_{q} \lambda_{N}} \\
\vdots & \vdots & & \vdots \\
{[N-1]_{q} \lambda_{1}^{N-2}} & {[N-1]_{q} \lambda_{2}^{N-2}} & \cdots & {[N-1]_{q} \lambda_{N}^{N-2}}
\end{array}
$$\right)
\]

with

$$
[n]_{q}=\frac{1-q^{n}}{1-q}
$$

We shall also need two diagonal matrices $A(\lambda)=\operatorname{diag}\left(A_{1}, A_{2}, \ldots, A_{N}\right)$ and $A^{\prime}(\lambda)=$ $\operatorname{diag}\left(A_{1}^{\prime}, A_{2}^{\prime}, \ldots, A_{N}^{\prime}\right)$ defined by

$$
A_{i}=\prod_{j \neq i} \frac{q \lambda_{i}-\lambda_{j}}{\lambda_{i}-\lambda_{j}}, \quad A_{i}^{\prime}=\prod_{j \neq i}\left(q \lambda_{i}-\lambda_{j}\right)
$$

With these notations one can check that $V$ can be written as

$$
\begin{equation*}
V=-\operatorname{Van}(\lambda) A^{\prime-1} \tilde{\Lambda} A^{\prime} \tag{5.3}
\end{equation*}
$$

where $\tilde{\Lambda}$ is a matrix of Calogero-Moser type

$$
\begin{align*}
& \tilde{\Lambda}_{i j}=\frac{A_{i}(\lambda)}{\lambda_{i}-q \lambda_{j}} \quad \text { for } i \neq j  \tag{5.4}\\
& \tilde{\Lambda}_{i i}=\frac{1-A_{i}(\lambda)}{\lambda_{i}(q-1)} \tag{5.5}
\end{align*}
$$

From (5.3) it easily follows that

$$
\begin{equation*}
\operatorname{Van}(q \lambda)=\operatorname{Van}(\lambda) A^{\prime-1}(E+(1-q) \tilde{\Lambda} \Lambda) A^{\prime} \tag{5.6}
\end{equation*}
$$

Now, using (5.2),(5.3) and (5.6) and the fact that $A^{\prime}, \Lambda$ and $\alpha$ are diagonal matrices (and so, in particular, they commute) we get the following formula for $\tau_{W}^{q}$ :

$$
\begin{align*}
\tau_{W}^{q}= & \operatorname{det}(\operatorname{Van}(\lambda)) \operatorname{det}\left(x(E+(1-q) \tilde{\Lambda} \Lambda)-\tilde{\Lambda}+\alpha \exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)\right. \\
& \left.+\frac{\exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)-E}{1-q} \Lambda^{-1}\right) \tag{5.7}
\end{align*}
$$

From (5.6) it follows that

$$
\operatorname{det}(E+(1-q) \tilde{\Lambda} \Lambda)=q^{N(N-1) / 2} \neq 0
$$

thus we can define

$$
\begin{align*}
X_{t}= & (E+(1-q) \tilde{\Lambda} \Lambda)^{-1}\left(\tilde{\Lambda}-\alpha \exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)\right. \\
& \left.+\frac{E-\exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)}{1-q} \Lambda^{-1}\right) \tag{5.8}
\end{align*}
$$

In particular, for $t=0$, we have

$$
\begin{equation*}
X_{0}=(E+(1-q) \tilde{\Lambda} \Lambda)^{-1}(\tilde{\Lambda}-\alpha) \tag{5.9}
\end{equation*}
$$

$X_{t}$ and $X_{0}$ are connected by

$$
\begin{equation*}
X_{t}=X_{0} \exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)+\frac{E-\exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)}{1-q} \Lambda^{-1} \tag{5.10}
\end{equation*}
$$

From the last equality we get

$$
X_{t-\left[z^{-1}\right]}=\left(X_{t}(z E-\Lambda)+E\right)(z E-q \Lambda)^{-1}
$$

and thus we can finally write explicit formulae (cf. $[40,42]$ ) for the tau function and the wave function

$$
\begin{align*}
\tau_{W}^{q}(x, t)= & \operatorname{det}(\operatorname{Van}(q \lambda)) \operatorname{det}\left(x E-X_{0} \exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)\right. \\
& \left.+\frac{\exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)-E}{1-q} \Lambda^{-1}\right)  \tag{5.11}\\
\Psi_{W}^{q}(x, t, z)= & \frac{\operatorname{det}\left(x z E-x q \Lambda-z X_{t}+X_{t} \Lambda-E\right)}{\operatorname{det}\left(x E-X_{t}\right) \operatorname{det}(z E-q \Lambda)} \mathrm{e}_{q}^{x z} \exp \left(\sum_{k=1}^{\infty} t_{k} z^{k}\right) \tag{5.12}
\end{align*}
$$

One can check that the matrices $\Lambda, \tilde{\Lambda}$ and $X_{t}$ satisfy the following relations:

$$
\begin{aligned}
& {[\Lambda, \tilde{\Lambda}]_{q}+E=A T, \quad\left[X_{t}, \Lambda\right]_{q}-E=\left(\left[X_{0}, \Lambda\right]-E\right) \exp \left(\sum t_{i}\left(1-q^{i}\right) \Lambda^{i}\right)} \\
& {\left[X_{0}, \Lambda\right]_{q}-E=-(E+(1-q) \tilde{\Lambda} \Lambda)^{-1} A T\left(E+(q-1) \Lambda X_{0}\right)}
\end{aligned}
$$

where $[P, Q]_{q}=P Q-q Q P$ denotes the $q$-commutator and

$$
T=T_{N}=\left(\begin{array}{ccc}
1 & \ldots & 1 \\
\vdots & & \vdots \\
1 & \ldots & 1
\end{array}\right)
$$

In particular, we have

$$
\operatorname{rank}\left(\left[X_{t}, \Lambda\right]_{q}-E\right)=1
$$

Our next goal will be to extend the symmetry in the adelic Grassmannian to the $q \neq 1$ case for a generic plane $W \in G r_{q}^{\text {ad }}$ of the form (5.1). Before that, we shall formulate a technical lemma.

Lemma 5.1. In the notations above, the identity

$$
\begin{equation*}
(E+(1-q) \tilde{\Lambda} \Lambda) A T=q^{N-1} A T \tag{5.13}
\end{equation*}
$$

holds.

Proof. Equality (5.13) is equivalent to

$$
\begin{equation*}
\sum_{k=1}^{N} \frac{\lambda_{k}}{\lambda_{s}-q \lambda_{k}} \prod_{i \neq k} \frac{q \lambda_{k}-\lambda_{i}}{\lambda_{k}-\lambda_{i}}=\frac{q^{N-1}}{1-q} \tag{5.14}
\end{equation*}
$$

The left-hand side of (5.14) can be rewritten as

$$
\frac{1}{\operatorname{det}(\operatorname{Van}(\lambda))}\left[\sum_{k=1}^{N} \frac{\lambda_{k}}{\lambda_{s}-q \lambda_{k}} \operatorname{det}\left(\operatorname{Van}\left(\lambda_{1}, \lambda_{2}, \ldots, q \lambda_{k}, \ldots, \lambda_{N}\right)\right)\right]=\frac{F(\lambda)}{\operatorname{det}(\operatorname{Van}(\lambda))}
$$

$F(\lambda)$ is a polynomial in $\left\{\lambda_{i}\right\}$ which is zero for $\lambda_{i}=\lambda_{j}$, hence $\operatorname{det}(\operatorname{Van}(\lambda)) / F(\lambda)$. But since $\operatorname{det}(\operatorname{Van}(\lambda))$ and $F(\lambda)$ have the same degree, it follows that the left-hand side of $(5.14)$ is a constant, which depends only on $q$ and $N$. Taking $\lambda_{s} \rightarrow 0$, (5.14) reduces to

$$
\sum_{k \neq s i \neq k, s} \prod_{k} \frac{q \lambda_{k}-\lambda_{i}}{\lambda_{k}-\lambda_{i}}=[N-1]_{q}
$$

Remembering that the left-hand side does not depend on $\left\{\lambda_{i}\right\}$, one can easily prove the last equality by induction.

Now, we are ready to characterize the planes of the form (5.1) by the next proposition.
Proposition 5.2. Let $X$ and $Y$ be two $n \times n$ matrices, such that the eigenvalues of $Y$ are $q$-distinct and

$$
\operatorname{rank}\left([X, Y]_{q}+E_{n}\right)=1
$$

Then, there exists $N \leq n$ and a matrix $U \in G L(n, \mathbb{C})$ such that

$$
Y=-U \operatorname{diag}(\underbrace{\lambda_{1}, \ldots, \lambda_{N}}_{\Lambda}, \underbrace{\lambda_{N+1}, \ldots, \lambda_{n}}_{\Lambda^{\prime}}) U^{-1}=-U\left(\begin{array}{cc}
\Lambda & 0 \\
0 & \Lambda^{\prime}
\end{array}\right) U^{-1}
$$

and $X$ can be written in the block form

$$
X=U\left(\begin{array}{cc}
X_{0} & * \\
0 & \Lambda^{\prime \prime}
\end{array}\right) U^{-1}
$$

with $X_{0}=\left(E_{N}+(1-q) \tilde{\Lambda} \Lambda\right)^{-1}(\tilde{\Lambda}-\alpha)$, the $N \times N$ matrix given by (5.9) for some diagonal matrix $\alpha$, and $\Lambda^{\prime \prime}=\left((1-q) \Lambda^{\prime}\right)^{-1}$. Defining a plane $W=W(X, Y) \in G r_{q}^{\text {ad }}$ by (5.1), its wave function at $t=0$ is given by

$$
\bar{\Psi}_{W}^{q}(x, z)=\bar{\Psi}^{q}(x, z, X, Y)=\frac{\operatorname{det}\left(x z E_{n}+x q Y-z X-X Y-E_{n}\right)}{\operatorname{det}\left(x E_{n}-X\right) \operatorname{det}\left(z E_{n}+q Y\right)} e_{q}^{x z}
$$

Proof. We can diagonalize the matrix $Y$ by a matrix $U_{1}$ and write

$$
\left[U_{1}^{-1} X U_{1}, \operatorname{diag}\left(\lambda_{1}, \ldots, \lambda_{n}\right)\right]_{q}-E_{n}=S^{\prime} T_{n} S^{\prime \prime}
$$

where $Y=-U_{1} \operatorname{diag}\left(\lambda_{1}, \ldots, \lambda_{n}\right) U_{1}^{-1}$, and $S^{\prime}$ and $S^{\prime \prime}$ are diagonal matrices (we still have the freedom to conjugate by diagonal matrices). Suppose that $S_{i}^{\prime} \neq 0$ for $i=1,2, \ldots, N$ and $S_{i}^{\prime}=0$ for $i=N+1, \ldots, n$. Then $X$ is of the form

$$
X=U_{1}\left(\begin{array}{cc}
X^{\prime} & * \\
0 & \Lambda^{\prime \prime}
\end{array}\right) U_{1}^{-1}
$$

and conjugating by diagonal matrices we can make $S_{i}^{\prime}$ (for $i=1, \ldots, N$ ) as arbitrary non-zero numbers. Let us fix $S_{i}^{\prime}=-A_{i}(\lambda)$. Thus we get

$$
\begin{equation*}
\left[X^{\prime}, \Lambda\right]_{q}-E_{N}=-A T_{N} S \tag{5.15}
\end{equation*}
$$

for some $N \times N$ matrix $S$. If we put

$$
\alpha=\tilde{\Lambda}-\left(E_{N}+(1-q) \tilde{\Lambda} \Lambda\right) X^{\prime}
$$

and multiply (5.15) to the left by $\left(E_{N}+(1-q) \tilde{\Lambda} \Lambda\right)$, using Lemma 5.1, we obtain

$$
[\Lambda, \alpha]=A T_{N}\left(E_{N}+(q-1) \Lambda X^{\prime}-q^{N-1} S\right)
$$

From the last equality it follows that $\alpha$ is a diagonal matrix. Since

$$
\bar{\Psi}^{q}(x, z, X, Y)=\bar{\Psi}^{q}\left(x, z, X^{\prime},-\Lambda\right)
$$

the rest of the argument is clear from (5.12).
As an immediate corollary of Proposition 5.2, we can state the main result of this section.
Theorem 5.3. Let $X$ and $Y$ be $n \times n$ matrices which have $q$-different eigenvalues and satisfy

$$
\operatorname{rank}\left([X, Y]_{q}+E_{n}\right)=1
$$

Let $W=W(X, Y)$ and $W^{\prime}=W^{\prime}\left(-q Y^{t},-q^{-1} X^{t}\right)$ denote the planes constructed in Proposition 5.2. Then we have

$$
\bar{\Psi}_{W}^{q}(x, z)=\bar{\Psi}_{W^{\prime}}^{q}(z, x)
$$

i.e., on pair of matrices, the bispectral involution corresponds to the map

$$
\beta:(X, Y) \rightarrow\left(-q Y^{t},-q^{-1} X^{t}\right)
$$

Remark 5.4. Following Wilson [42], let us denote by $V_{n}$ the complex vector space of pairs $(X, Y)$, where $X$ and $Y$ are $n \times n$ matrices, and by $\tilde{C}_{n}^{q}$ the sub-variety of $V_{n}$, consisting of all $(X, Y)$ satisfying the equation

$$
\begin{equation*}
\operatorname{rank}\left([X, Y]_{q}+E_{n}\right)=1 \tag{5.16}
\end{equation*}
$$

The group $G L(n, \mathbb{C})$ acts on $V_{n}$ by simultaneous conjugation of $X$ and $Y$. Clearly this action preserves (5.16). Let $C_{n}^{q}$ stand for the quotient space $\tilde{C}_{n}^{q} / G L(n, \mathbb{C})$. Formula (5.10) suggests to introduce q-analogues of the Calogero-Moser flows on $C_{n}^{q}$, induced by the $G L(n, \mathbb{C})$ invariant flows on $\tilde{C}_{n}^{q}$

$$
\begin{align*}
(X, Y) \rightarrow & \left(X \exp \left(\sum t_{i}\left(1-q^{i}\right)(-Y)^{i}\right)\right. \\
& \left.+\frac{E-\exp \left(\sum t_{i}\left(1-q^{i}\right)(-Y)^{i}\right)}{1-q}(-Y)^{-1}, Y\right) \tag{5.17}
\end{align*}
$$

One can check that the above formula defines properly commutative flows on $V_{n}$, which preserve the condition (5.16). However, in the case $q \neq 1$ these flows are not Hamiltonian (in the standard coordinates), and thus the reduction procedure of [29] cannot be easily applied. In the next section, we shall write the corresponding dynamical system on the reduced phase space in a Hamiltonian form, using the approach of Shiota [40].

## 6. Rational solutions to $q-K P$ hierarchy and the corresponding deformation of Calogero-Moser hierarchy

In [3] Airault et al. discovered an amazing relation between equations of KdV type and the Calogero-Moser system. Namely, they showed that the poles of a rational solution to the KdV or Boussinesq equation that vanishes at infinity is described by the Calogero-Moser system with inverse square potential, with some constraint on the configuration of poles. Krichever [32] observed that the poles of the rational solutions of the KP equation that vanish at $x=\infty$, move according to the Calogero-Moser system with no constraint and wrote down explicit formulae for these solutions. Finally, Shiota [40] extended this phenomenon to the whole KP hierarchy. The aim of the present section is to find the system of equations for the poles of the rational solutions to the $q$-KP hierarchy. Since the poles come from zeros of the tau function, let

$$
\begin{equation*}
\tau^{q}(x, t)=\left(x-x_{1}(t)\right)\left(x-x_{2}(t)\right) \cdots\left(x-x_{N}(t)\right) \tag{6.1}
\end{equation*}
$$

be a $q$-tau function of the KP hierarchy, which is a polynomial in $x$. We may assume that $\partial x_{j} / \partial t_{1} \neq 0$ for $j=1,2, \ldots, N$. Indeed, if $\partial x_{j} / \partial t_{1}=0$ for some $j$, then it is not difficult to see that $\partial x_{j} / \partial t_{n}=0$ for any $n$ (cf. (6.9),(6.10) and (6.12) below), which means that $\left(x-x_{j}\right)$ is just an unessential factor in the tau function. We shall suppose also that $x_{i} \neq q^{k} x_{j}$ for $i \neq j$ and $k=0,1$. This is a natural restriction since in the limit $q \rightarrow 1$ it reduces to $x_{i} \neq x_{j}$ for $i \neq j$, which can always be achieved by picking an appropriate neighbourhood of the $\left\{t_{i}\right\}$ 's, see $[39,40]$. Let us denote by $A_{i}=A_{i}\left(x_{1}, x_{2}, \ldots, x_{N}\right)$ the expression from the previous section

$$
\begin{equation*}
A_{i}=\prod_{j \neq i} \frac{q x_{i}-x_{j}}{x_{i}-x_{j}} \tag{6.2}
\end{equation*}
$$

and introduce $y_{1}, y_{2}, \ldots, y_{N}$ by

$$
\begin{equation*}
-x_{i}^{\prime}=A_{i} \mathrm{e}^{(1-q) x_{i} y_{i}} \tag{6.3}
\end{equation*}
$$

where for simplicity we have posed ${ }^{\prime}=\partial / \partial t_{1}$. We define the $q$-deformed Calogero-Moser matrix $Y$ by

$$
\begin{align*}
& Y_{i j}=-\frac{x_{i}^{\prime}}{x_{i}-q x_{j}}=\frac{A_{i} \mathrm{e}^{(1-q) x_{i} y_{i}}}{x_{i}-q x_{j}}, \quad \text { for } i \neq j  \tag{6.4}\\
& Y_{i i}=\frac{1+x_{i}^{\prime}}{x_{i}(q-1)}=\frac{1-A_{i} \mathrm{e}^{(1-q) x_{i} y_{i}}}{x_{i}(q-1)} \tag{6.5}
\end{align*}
$$

With these notations we can state the main result of this section.
Theorem 6.1. Let $\tau^{q}(x, t)=\prod_{i=1}^{N}\left(x-x_{i}(t)\right)$ be a tau function of the $q-K P$ hierarchy, which is a monic polynomial in $x$. Then the motion of the zeros of $\tau^{q}$ is governed by a hierarchy of Hamiltonian systems, which is a q-deformation of the Calogero-Moser hierarchy. Precisely, if we define

$$
H_{n}=(-1)^{n} \frac{[n]_{q}}{n} \operatorname{tr}\left(Y^{n}\right)
$$

we have

$$
\begin{equation*}
\frac{\partial}{\partial t_{n}}\binom{x_{i}}{y_{i}}=\binom{\partial H_{n} / \partial y_{i}}{-\partial H_{n} / \partial x_{i}}, \quad n=1,2, \ldots \tag{6.6}
\end{equation*}
$$

Proof. Consider the wave function

$$
\begin{equation*}
\Psi^{q}(x, t, z)=\left(\sum_{k=0}^{\infty} \psi_{k} z^{-k}\right) e_{q}^{x z} \exp \left(\sum_{k=1}^{\infty} t_{k} z^{k}\right) \tag{6.7}
\end{equation*}
$$

where $\psi_{0}=1$ and $\psi_{k}, k>0$, is given by

$$
\begin{equation*}
\psi_{k}=\frac{p_{k}(-\tilde{\partial}) \tau^{q}}{\tau^{q}} \tag{6.8}
\end{equation*}
$$

For our special choice (6.1) of the tau function we can write

$$
\begin{equation*}
\psi_{k}=\sum_{i=1}^{N} \frac{w_{k, i}}{x-x_{i}}, \quad k \geq 1 \tag{6.9}
\end{equation*}
$$

and in particular, for $k=1$ formula (6.8) gives

$$
\begin{equation*}
w_{1, i}=-x_{i}^{\prime} \tag{6.10}
\end{equation*}
$$

Putting (6.1) and (6.7) in (2.6), and comparing the coefficients of $z^{-k}$, we obtain

$$
\begin{equation*}
\psi_{k+1}+\frac{\partial \psi_{k}}{\partial t_{1}}=\psi_{k+1}(x q)+D_{q, x} \psi_{k}+x(q-1) \sum_{i=1}^{N} \frac{x_{i}^{\prime}}{\left(x-x_{i}\right)\left(x q-x_{i}\right)} \psi_{k} \tag{6.11}
\end{equation*}
$$

For $k>0$, the coefficient of $\left(x-x_{i} / q\right)^{-1}$ in (6.11) gives the reccurence relation

$$
\begin{equation*}
-\frac{w_{k+1, i}}{q}=\frac{1+x_{i}^{\prime}}{x_{i}(q-1)} w_{k, i}-\sum_{j \neq i} \frac{x_{i}^{\prime}}{x_{i}-q x_{j}} w_{k, j} \tag{6.12}
\end{equation*}
$$

and the coefficient of $\left(x-x_{i}\right)^{-1}$ in (6.11) gives

$$
\begin{align*}
w_{k+1, i}+\frac{\partial w_{k, i}}{\partial t_{1}}= & \left(-\frac{1+x_{i}^{\prime}}{x_{i}(q-1)}+\sum_{j \neq i} \frac{(q-1) x_{i} x_{j}^{\prime}}{\left(x_{i}-x_{j}\right)\left(x_{i} q-x_{j}\right)}\right) w_{k, i} \\
& +\sum_{j \neq i} \frac{x_{i}^{\prime}}{x_{i}-x_{j}} w_{k, j} \tag{6.13}
\end{align*}
$$

Denoting $X=\operatorname{diag}\left(x_{1}, x_{2}, \ldots, x_{N}\right), w_{k}=\left(w_{k, 1}, \ldots, w_{k, N}\right)^{\mathrm{t}}, \mathbf{e}=(1,1, \ldots, 1)^{\mathrm{t}}$ we have from (6.10) and (6.12)

$$
\begin{equation*}
w_{k}=(-q Y)^{k-1} X^{\prime} \mathbf{e} \tag{6.14}
\end{equation*}
$$

where $Y$ is the $q$-deformed Calogero-Moser matrix defined by (6.4) and (6.5). Eliminating $w_{k+1, i}$ from Eqs. (6.12) and (6.13) we obtain

$$
\begin{equation*}
\frac{\partial w_{k, i}}{\partial t_{1}}=\left(\frac{1+x_{i}^{\prime}}{x_{i}}+\sum_{j \neq i} \frac{(q-1) x_{i} x_{j}^{\prime}}{\left(x_{i}-x_{j}\right)\left(x_{i} q-x_{j}\right)}\right) w_{k, i}-\sum_{j \neq i} \frac{(q-1) x_{i} x_{i}^{\prime}}{\left(x_{i}-x_{j}\right)\left(x_{i}-q x_{j}\right)} w_{k, j} \tag{6.15}
\end{equation*}
$$

Let

$$
\Psi^{q *}(x, t, z)=\left(1+\sum_{k=1}^{\infty} \psi_{k}^{*} z^{-k}\right) \mathrm{e}_{1 / q}^{-x z} \exp \left(-\sum_{k=1}^{\infty} t_{k} z^{k}\right)
$$

be the $q$-adjoint wave function (see [25]). Writing $\psi_{k}^{*}$ as

$$
\psi_{k}^{*}=\sum_{i=1}^{N} \frac{w_{k, i}^{*}}{x-x_{i}}
$$

and comparing the coefficients of $\left(x-q x_{i}\right)^{-1}$ in

$$
\partial_{1} \Psi^{q *}=-\left(\left.L\right|_{x / q}\right)_{+}^{*} \Psi^{q *}=\left(D_{1 / q, x}-a_{0}(x / q)\right) \Psi^{q *}
$$

we obtain as above

$$
\begin{equation*}
w_{k}^{*}=-X^{\prime}\left(-Y^{t}\right)^{k-1} \mathbf{e}, \tag{6.16}
\end{equation*}
$$

where $w_{k}^{*}=\left(w_{k, 1}^{*}, w_{k, 2}^{*}, \ldots, w_{k, N}^{*}\right)^{t}$. Now, we compute the coefficients of $D_{q, x}^{-1}$ in the equation

$$
\begin{equation*}
\partial_{n} S=-\left(S D_{q, x}^{n} S^{-1}\right)_{-} S \tag{6.17}
\end{equation*}
$$

The left-hand side is

$$
\begin{align*}
\partial_{n} S & =\sum_{k=1}^{\infty} \sum_{i=1}^{N}\left(\frac{\left(\partial_{n} x_{i}\right) w_{k, i}}{\left(x-x_{i}\right)^{2}}+\frac{\partial_{n} w_{k, i}}{x-x_{i}}\right) D_{q, x}^{-k} \\
& =\left(\frac{x_{i}^{\prime}\left(\partial_{n} x_{i}\right)}{\left(x-x_{i}\right)^{2}}+\frac{\partial_{n} x_{i}^{\prime}}{x-x_{i}}\right) D_{q, x}^{-1}+\mathrm{O}\left(D_{q, x}^{-2}\right) . \tag{6.18}
\end{align*}
$$

On the other hand, from the definition of the $q$-adjoint wave function we have

$$
S^{-1}=\sum_{j=0}^{\infty} D_{q, x}^{-j} \cdot \psi_{j}^{*}(x q)
$$

so the right-hand side of (6.17) becomes

$$
\begin{aligned}
-\left(S D_{q, x}^{n} S^{-1}\right)_{-} S & =-\left(\sum_{k+l \geq n+1} \psi_{k} D_{q, x}^{n-k-l} \cdot \psi_{l}^{*}(x q)\right)\left(1+\sum_{k \geq 1} \psi_{k} D_{q, x}^{-k}\right) \\
& =-\sum_{k+l=n+1} \psi_{k} \psi_{l}^{*} D_{q, x}^{-1}+\mathrm{O}\left(D_{q, x}^{-2}\right)
\end{aligned}
$$

and thus

$$
\frac{x_{i}^{\prime} \partial_{n} x_{i}}{\left(x-x_{i}\right)^{2}}+\frac{\partial_{n} x_{i}^{\prime}}{x-x_{i}}=-\sum_{k+l=n+1} \psi_{l}^{*} \psi_{k}
$$

Comparing the coefficients of $\left(x-x_{i}\right)^{-2}$ in the above identity, and using (6.14) and (6.16), we get

$$
\begin{aligned}
x_{i}^{\prime}\left(\partial_{n} x_{i}\right) & =-\sum_{k=1}^{n} w_{n+1-k, i}^{*} w_{k, i}=\sum_{k=1}^{n} w_{n+1-k}^{* t} E_{i i} w_{k} \\
& =(-1)^{n+1} \sum_{k=1}^{n} q^{k-1} \mathbf{e}^{t} Y^{n-k} X^{\prime} E_{i i} Y^{k-1} X^{\prime} \mathbf{e}
\end{aligned}
$$

Here, as usual, $E_{i j}$ denotes the matrix with 1 at the $(i, j)$ th entry, with all other entries zero. Since $X^{\prime} E_{i i}=x_{i}^{\prime} E_{i i}$, we can cancel $x_{i}^{\prime}$ and rewrite the above equality as

$$
\partial_{n} x_{i}=(-1)^{n+1} \operatorname{tr}\left(\sum_{k=1}^{n} q^{k-1} Y^{n-k} E_{i i} Y^{k-1} X^{\prime}\left(\begin{array}{ccc}
1 & \ldots & 1 \\
\vdots & & \vdots \\
1 & \ldots & 1
\end{array}\right)\right)
$$

Finally, replacing $X^{\prime}\left(\begin{array}{ccc}1 & \ldots & 1 \\ \vdots & & \vdots \\ 1 & \ldots & 1\end{array}\right)$ by $-(E+X Y-q Y X)$, and using the elementary properties of the trace operator we get

$$
\begin{align*}
\partial_{n} x_{i}= & (-1)^{n} \operatorname{tr}\left(\sum_{k=1}^{n} q^{k-1} Y^{n-k} E_{i i} Y^{k-1}(E+X Y-q Y X)\right) \\
= & (-1)^{n}\left(\sum_{k=1}^{n} q^{k-1} \operatorname{tr}\left(E_{i i} Y^{n-1}\right)+\sum_{k=1}^{n} q^{k-1} \operatorname{tr}\left(Y^{n+1-k} E_{i i} Y^{k-1} X\right)\right. \\
& \left.-\sum_{k=1}^{n} q^{k} \operatorname{tr}\left(Y^{n-k} E_{i i} Y^{k} X\right)\right) \\
= & (-1)^{n}[n]_{q} \operatorname{tr}\left(\left(E_{i i}+(1-q) E_{i i} X Y\right) Y^{n-1}\right) . \tag{6.19}
\end{align*}
$$

But since

$$
\frac{\partial Y}{\partial y_{i}}=E_{i i}+(1-q) E_{i i} X Y
$$

(6.19) gives the first equation in (6.6). To get the second equation, we need to represent 'nicely' the first flow $\partial / \partial t_{1}$ on the matrix $Y$, which is the content of the next lemma.

Lemma 6.2. The first flow $\partial / \partial t_{1}$ can be written in the Lax form

$$
\begin{equation*}
\frac{\partial Y}{\partial t_{1}}=[Y, M] \tag{6.20}
\end{equation*}
$$

where $M$ is another deformation of the Calogero-Moser matrix given by

$$
M_{i j}=-\frac{x_{i}^{\prime}}{x_{i}-x_{j}} \quad \text { for } i \neq j, \quad M_{i i}=\frac{1+x_{i}^{\prime}}{x_{i}(q-1)}+\sum_{k \neq i}\left(\frac{x_{k}^{\prime}}{x_{i} q-x_{k}}-\frac{x_{k}^{\prime}}{x_{i}-x_{k}}\right)
$$

Proof of Lemma 6.2. The equality (6.20) can be checked directly, using (6.10) and (6.15) for $k=1$, and the definition (6.4) and (6.5) of $Y$.

We can now finish the proof of Theorem 6.1. From (6.3),(6.19) and Lemma 6.2 one can easily deduce

$$
\begin{equation*}
\frac{\partial y_{i}}{\partial t_{n}}=(-1)^{n}[n]_{q} \operatorname{tr}\left(B Y^{n-1}\right) \tag{6.21}
\end{equation*}
$$

where

$$
\begin{aligned}
B= & \frac{1}{(q-1) x_{i} x_{i}^{\prime}}\left[E_{i i}, \hat{M}\right] \\
& +\frac{1}{x_{i}} E_{i i} Y+\frac{1}{x_{i}^{\prime}}\left(\hat{M} E_{i i} Y-Y E_{i i} \hat{M}\right)+\frac{1}{(q-1) x_{i}} \sum_{j} \frac{\partial \log A_{i}}{\partial x_{j}} E_{j j} \\
& -\left(\sum_{j} \frac{x_{j}}{x_{i}} \frac{\partial \log A_{i}}{\partial x_{j}} E_{j j}\right) Y-\frac{y_{i}}{x_{i}}\left(E_{i i}+(1-q) x_{i} E_{i i} Y\right),
\end{aligned}
$$

with $\hat{M}_{j k}=\left(1-\delta_{j k}\right) M_{j k}$. On the other hand, a direct computation shows that

$$
\begin{equation*}
B+\frac{\partial Y}{\partial x_{i}}=\left[\sum_{j \neq i} \frac{\partial \log A_{j}}{\partial x_{i}} E_{j j}+\frac{1}{(1-q) x_{i}} E_{i i}, Y\right] \tag{6.22}
\end{equation*}
$$

which combined with (6.21) gives the second equation in (6.6).
Remark 6.3 (The limiting case $q=1$ ). We should note that our choice of 'dual' variables $\left\{y_{i}\right\}$ does not reduce exactly to the standard one $\left\{\xi_{i}\right\}$ with $\xi_{i}=\partial x_{i} / \partial t_{2}$ in the classical case $q=1$. Indeed, in the limit $q \rightarrow 1$, from (6.4) and (6.5), it follows that

$$
\lim _{q \rightarrow 1} Y_{i j}=\frac{1}{x_{i}-x_{j}} \quad \text { for } i \neq j, \quad \lim _{q \rightarrow 1} Y_{i i}=\frac{\partial x_{i}}{\partial t_{2}}=y_{i}+\sum_{j \neq i} \frac{1}{x_{j}-x_{i}}
$$

i.e.

$$
\xi_{i}=y_{i}+\sum_{j \neq i} \frac{1}{x_{j}-x_{i}}
$$

From these relations, it is not difficult to see that the system of equations (6.6) is equivalent to Eq. (3) in [40].

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[^0]:    E-mail address: iliev @ agel.ucl.ac.be (P. Iliev)
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[^1]:    ${ }^{2}$ It is a tau function in $t$ in the sense of Sato theory for any $x$ fixed.

[^2]:    ${ }^{3}$ As usual : : means normal ordering, i.e. always pull the $q$-difference operator to the right.

[^3]:    ${ }^{4} G r^{\mathrm{rat}}$ is denoted by $G r_{1}$ in [38].

[^4]:    ${ }^{5}$ These transformations are sometimes referred to as gauge transformations.

[^5]:    ${ }^{6}$ One should be careful here because the same condition can be written as a condition at the point $\lambda_{k} q^{-m}$ and then the order will be $s_{k}+m$.

[^6]:    ${ }^{7}$ In the rest of the paper we shall briefly call $\left\{\lambda_{i}\right\}$ ' $q$-different' if they are different and $\lambda_{i} \neq q \lambda_{j}$ for $i \neq j$.

